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NTE1892 & NTE1892A Integrated Circuit Dual Bi-Directional Motor Driver with Brake Function and Thermal Shutdown

Description:

The NTE1892 and NTE1892A are bi-directional motor drivers in a 12-Lead SIP type package and consists of two full bridge drivers designed for use in a two DC motor control circuit.

Features:

- Two Separate Full Bridge Drivers (Only one circuit can be switched by the Select (S_E) Input).
- Wide Operating Voltage Range: V_{CC} = 4V to 16V
- TTL, PMOS, CMOS Outputs, Capable of Direct Drive
- Low Output Saturation Voltage
- Built-in Clamp Diode
- High Output Drive Current: I_{Omax} = ±2A
- Braking Mode Input
- Internal Thermal Shutdown Protection

Applications:

- Audio Tape Deck Player
- Radio/Cassette Player
- Video Cassette Recorder
- Home Equipment Use

Absolute Maximum Ratings: (T_A = +25°C unless otherwise specified)

| | |
|---|------------------------------|
| Supply Voltage 1, V _{CC(1)} | -0.5V to +18V |
| Supply Voltage 2 (NTE1892 Only , Note 1), V _{CC(2)} | -0.5V to +18V |
| Driver Supply Voltage, V _{CC'} | -0.5V to +18V |
| Input Voltage, V _i | 0 to V _{CC} V |
| Output Voltage, V _O | -2V to V _{CC} +2.5V |
| Peak Output Current (t _{op} = 10ms, relative cycle 0.2Hz Max), I _{Omax} | |
| NTE1892 | ±2.0A |
| NTE1892A | ±1.2A |
| Continuous Output Current 1, I _{O(1)} | ± 330mA |
| Continuous Output Current 2 (NTE1892 Only , Note 1), I _{O(2)} | ± 600mA |
| Power Dissipation (T _A = +75°C), P _D | |
| NTE1892 | 1.6W |
| NTE1892A | 830mW |
| Operating Temperature Range, T _{opr} | |
| NTE1892 | -10° to +75°C |
| NTE1892A | -20° to +75°C |
| Storage Temperature Range, T _{stg} | -55° to +125°C |

Note 1. With external heat sink (3000mm² x 1.5mm)

Recommended Operating Conditions: ($T_A = +25^\circ\text{C}$ unless otherwise specified)

| Parameter | Symbol | Test Conditions | Min | Typ | Max | Unit |
|-----------------------------------|----------------------|-----------------------|-----|-----|-----------|------------------|
| Supply Voltage | V_{CC} | | 4 | 12 | 16 | V |
| Output Current | I_O | | - | - | ± 300 | mA |
| High-Level Input Voltage | V_{IH} | Input S_1, S_2, S_E | 2 | - | V_{CC} | V |
| Low-Level Input Voltage | V_{IL} | Input S_1, S_2, S_E | 0 | - | 0.4 | V |
| Motor Braking Interval NTE1892 | t_s | | 10 | 100 | - | ms |
| NTE1892A | | | 100 | - | - | ms |
| Thermal Shutdown Temperature | $t_{j(\text{shut})}$ | $V_{CC} \geq 7V$ | - | 150 | - | $^\circ\text{C}$ |

Electrical Characteristics: ($T_A = +25^\circ\text{C}$ unless otherwise specified)

| Parameter | Symbol | Test Conditions | Min | Typ | Max | Unit | |
|---------------------------|----------------------|--|---|------|-----|---------------|---------------|
| Output Leakage Current | $I_{O(\text{LEAK})}$ | $V_{CC} = V_{CC'} = 18V, V_{S1} = V_{S2} = 0V, V_{SE} = 0V \text{ or } 2V$ | $V_O = 18V$ | - | - | 100 | μA |
| | | | $V_O = 0V$ | - | - | -100 | μA |
| High-Level Output Voltage | V_{OH} | $V_{CC} = V_{CC'} = 12V$ | $I_{OH(1)} = -200\text{mA}$ | 10.8 | - | - | V |
| | | | $I_{OH(1)} = -500\text{mA}$ | 10.7 | - | - | V |
| Low-Level Output Voltage | V_{OL} | $V_{CC} = V_{CC'} = 12V$ | $I_{OL} = 200\text{mA}$ | - | - | 0.5 | V |
| | | | $I_{OL} = 500\text{mA}$ | - | - | 1.35 | V |
| High-Level Input Current | I_{IH} | $V_{CC} = V_{CC'} = 12V, V_i = 2V$ | 50 | - | 120 | μA | |
| Low-Level Input Current | I_{IL} | $V_{CC} = V_{CC'} = 12V, V_i = 0V$ | 50 | - | 120 | μA | |
| Supply Current | I_{CC} | $V_{CC} = V_{CC'} = 12V$ | $V_{SE} = 0V, V_{S1} = V_{S2} = 0V$ | - | - | 10 | mA |
| | | | $V_{SE} = 0V, V_{S1} = 0V, V_{S2} = 2V$ | - | - | 20 | mA |

Function:

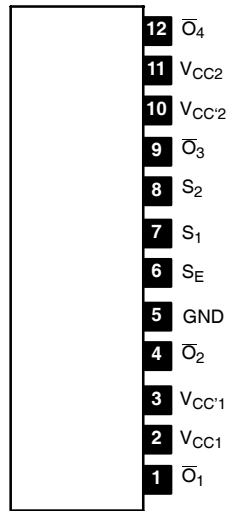
The NTE1892/NTE1892A, two full bridge motor driver, has the logic circuitry and the quasi-darlington power driver for bi-directional control of two DC motors operating at currents up to 2A.

The input S_E selects one of the bridges and S_1 and S_2 determines the output polarity.

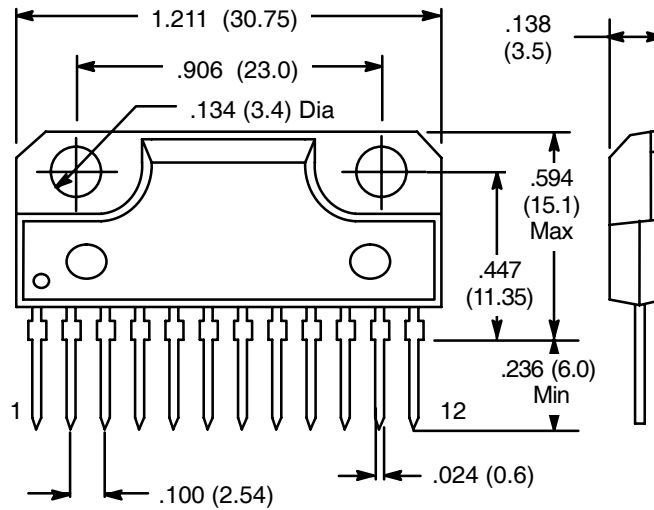
Logic Truth Table:

| Input | | | Output | | | | Note | |
|-------|-------|-------|-------------|-------------|-------------|-------------|-------------------------------|-------------------------------|
| S_E | S_1 | S_2 | \bar{O}_1 | \bar{O}_2 | \bar{O}_3 | \bar{O}_4 | Output \bar{O}_1, \bar{O}_2 | Output \bar{O}_3, \bar{O}_4 |
| 0 | 0 | 0 | OFF | OFF | OFF | OFF | OPEN | OPEN |
| 0 | 1 | 0 | 1 | 0 | OFF | OFF | Motor Forward | OPEN |
| 0 | 0 | 1 | 0 | 1 | OFF | OFF | Motor Reverse | OPEN |
| 0 | 1 | 1 | 0 | 0 | OFF | OFF | BRAKING | OPEN |
| 1 | 0 | 0 | OFF | OFF | OFF | OFF | OPEN | OPEN |
| 1 | 1 | 0 | OFF | OFF | 1 | 0 | OPEN | Motor Forward |
| 1 | 0 | 1 | OFF | OFF | 0 | 1 | OPEN | Motor Reverse |
| 1 | 1 | 1 | OFF | OFF | 0 | 0 | OPEN | BRAKING |

Pin Connection Diagram
(Front View)



NTE1892



NTE1892A

